# On Polynomial $\delta$-Type Functions and Approximation by Monotonic Polynomials 

Zalman Rubinstein*<br>Clark University, Department of Mathematics, Worcester, Massachusetts 01610

Received November 12, 1968

Some attention has been given in recent years to the problem of approximation of real functions by monotone polynomials. In 1965, O. Shisha [5] proved, among other things, the following result: If $1 \leqslant k \leqslant p$ and if a real function $f(x)$, defined on $[0,1]$, satisfies

$$
f^{(k)}(x) \geqslant 0, \quad\left|f^{(p)}(x)\right| \leqslant M, \quad \text { for } \quad 0 \leqslant x \leqslant 1,
$$

then for every integer $n(\geqslant p)$, there exists a real polynomial $Q_{n}(x)$ of degree not exceeding $n$ such that the inequalities

$$
Q_{n}^{(k)}(x) \geqslant 0
$$

and

$$
\begin{equation*}
\left|f(x)-Q_{n}(x)\right| \leqslant \frac{C}{n^{p-k}} w\left(f^{(p)}, \frac{1}{n}\right) \tag{1}
\end{equation*}
$$

hold for all $0 \leqslant x \leqslant 1$, where $C$ depends only upon $p$ and $k$ and $w(\phi, h)$ is the modulus of continuity of the function $\phi$.

Roulier [4], and Lorentz and Zeller [2] continued the investigation in this direction by relaxing, somewhat, the conditions on $f$, and by sharpening the estimate (1), particularly for large $n$.
In this note, we deal briefly with a related problem, namely, that of uniform approximation of a monotone continuous real-valued function by monotone polynomials, which, in addition, agree with the function on a finite set of points. Subsequently, we mention some applications.

The main theorems of this note are:
Theorem A. Let $0<x_{1}<\cdots<x_{n} \leqslant 1$ and $0<y_{1}<\cdots<y_{n}$ be fixed. There exists a polynomial $Q(x)$ such that
(a) $Q(0)=0, Q\left(x_{i}\right)=y_{i}, i=1,2, \ldots, n$;
(b) $Q^{\prime}(x) \geqslant 0$ for all real $x$.

* The author acknowledges partial support of NSF Grant GP-5221, GP-11881.

Theorem B. Any strictly increasing continuous function defined on $[0,1]$, can be uniformly approximated, as closely as desired, by a strictly increasing polynomial and in such a way that the two functions agree on an arbitrarily given finite set of points.

In the proof of Theorem $A$, we shall need the following:
Lemma 1. Let $r, 0<r<1$, be a rational number. The polynomial

$$
P_{r}(x)=\frac{x^{k}(1-x)^{m-k}}{r^{k}(1-r)^{m-k}}
$$

where $r=k / m$ ( $k$ and $m$ positive even integers), has the following properties:
(a) $P_{r}(0)=P_{r}(1)=0, P_{r}(r)=1, P_{r}(x) \geqslant 0$ for all real $x$.
(b) $P_{r}(x)$ is strictly increasing in the interval $[0, r]$ and strictly decreasing in the interval $[r, 1]$.

Lemma 2. The polynomials

$$
Q_{r, n}(x)=c_{n} P_{r}^{n}(x), \quad n=1,2, \ldots
$$

where

$$
c_{n}=\left(\int_{0}^{1} P_{r}^{n}(x) d x\right)^{-1}=(m n+1)\binom{m n}{k n} r^{k n}(1-r)^{m n-k n}
$$

have the following properties:
(a) $Q_{r, n}(0)=Q_{r, n}(1)=0, Q_{r, n}(r)=c_{n}, Q_{r, n}(x) \geqslant 0$ for all real $x$.
(b) $Q_{r, n}(x)$ is strictly increasing in the interval $[0, r]$ and strictly decreasing in the interval $[r, 1]$.
(c) $\int_{0}^{1} Q_{r, n}(x) d x=1$.
(d) $\lim _{n \rightarrow \infty} Q_{r, n}(x)=0$ for $x \in[0,1], x \neq r$.

Proof. (a), (b), and (c) follow immediately by Lemma 1 and the definition of $c_{n}$. To verify (d), we notice that by the binomial formula,

$$
\binom{m n}{k n} r^{k n}(1-r)^{m n-k n}<1
$$

Therefore, $c_{n}<m n+1$ and, since $0 \leqslant P_{r}(x)<1$ for $x \in[0,1], x \neq r$, it follows that $\lim _{n \rightarrow \infty}\left[c_{n} P_{r}^{n}(x)\right]=0$.

Remark. Actually, by performing a more rigorous calculation with the help of Stirling's formula, one obtains the asymptotic estimate

$$
c_{n} \sim[2 \pi r(1-r)]^{-1 / 2}(m n)^{1 / 2}
$$

Proof of Theorem A. Consider the polynomial

$$
\begin{equation*}
Q(x)=\sum_{j=1}^{n} \alpha_{j} \int_{0}^{x} Q_{r_{j}, n_{j}}(t) d t \tag{2}
\end{equation*}
$$

where $\alpha_{j}, r_{j}$ and $n_{j}$ are defined below and where $Q_{r_{j}, n_{j}}(x)$ is as in Lemma 2.
It is clear that $Q(0)=0$ and that $Q^{\prime}(x) \geqslant 0$ for all real $x$ if all $\alpha_{j}$ are $\geqslant 0$.
Set $\quad y=\left(y_{1}, y_{2}, \ldots, y_{n}\right), \quad c_{i j}=\int_{0}^{x_{i}} Q_{r_{j}, n_{j}}(t) d t, \quad u_{j}=\left(c_{1 j}, c_{2 j}, \ldots, c_{n j}\right)$, $i, j=1,2, \ldots, n$.

To satisfy condition (a), we have to solve the system

$$
\begin{equation*}
\sum_{j=1}^{n} \alpha_{j} u_{j}=y \tag{3}
\end{equation*}
$$

The point $y \in R_{n}$ is a strictly increasing sequence of positive numbers and for each $j$, the point $u_{j} \in R_{n}$ is a strictly increasing sequence of positive numbers bounded above by unity. It follows that the point $y$ lies interior to the infinite "wedge" in $R_{n}$ with vertex at the origin, spanned by the vectors $(0,0, \ldots, 0,1),(0,0, \ldots, 0,1,1), \ldots,(1,1, \ldots, 1)$, which we shall denote by $e_{1}, e_{2}, \ldots, e_{n}$, respectively. One deduces that the system (3) will have a strictly positive solution ( $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{n}$ ) (that is, one with all $\alpha_{j}>0$ ) provided the vectors $u_{j}$ are sufficiently close to the vectors $e_{j}$. To this end, we choose the $\delta$-type polynomials $Q_{r_{j}, n_{j}}(x)$ in the following manner. For a given $j, 1 \leqslant j \leqslant n$, and a given positive $\epsilon<1$, we select an $r_{j}$ such that $x_{n-j}<r_{j}<x_{n-j+1}$ and construct a polynomial $Q_{r_{j}, n_{j}}(x)$ such that

$$
Q_{r_{j}, n_{j}}(x)<\epsilon \quad \text { for } \quad 0 \leqslant x \leqslant x_{n-j} \text { and for } \quad x_{n-j+1} \leqslant x \leqslant x_{n}
$$

It follows that

$$
\begin{array}{rll}
0<c_{i j}<\epsilon & \text { for } & 1 \leqslant i \leqslant n-j \\
1-\epsilon<c_{i j} \leqslant 1 & \text { for } & n-j+1 \leqslant i \leqslant n .
\end{array}
$$

It is clear that $u_{j} \rightarrow e_{j}$ as $\epsilon \rightarrow 0$.
Now, the linear system

$$
\sum_{j=1}^{n} \beta_{j} e_{j}=y
$$

has the positive solution

$$
\left(\beta_{1}, \beta_{2}, \ldots, \beta_{n}\right)=\left(y_{n}-y_{n-1}, y_{n-1}-y_{n-2}, \ldots, y_{2}-y_{1}, y_{1}\right)
$$

By continuity, it follows that for sufficiently small $\epsilon=\epsilon(y)$, the linear system (3) has a positive solution ( $\alpha_{1}, \alpha_{2}, \ldots, \alpha_{n}$ ). This concludes the proof.

Theorem B is, of course, a direct consequence of Theorem A.
We shall mention, now, a few consequences of the previous results.
Corollary 1. Let $J=\left[x_{0}, y_{0}\right]\left(0 \leqslant x_{0}<y_{0} \leqslant 1, x_{0}+y_{0}<1\right)$. For every positive number $M$ there exists a polynomial $P(x)(\not \equiv 0)$ which is nonnegative for all $x$ such that

$$
\int_{J} P(x) d x=M \int_{[0,1]-J} P(x) d x
$$

Proof. Let $P(x)=Q^{\prime}(x)$, where $Q(x)$ is a polynomial as in Theorem A, satisfying

$$
Q(0)=0, \quad Q\left(x_{0}\right)=\frac{\delta}{M+1}, \quad Q\left(y_{0}\right)=\frac{M+\delta}{M+1}, \quad Q(1)=1
$$

with $0<\delta<1$ if $x_{0}>0, y_{0}<1 ; \delta=0$ if $x_{0}=0$ and $\delta=1$ if $y_{0}=1$. We deduce that

$$
\int_{J} P(x) d x=Q\left(y_{0}\right)-Q\left(x_{0}\right)=\frac{M}{M+1}
$$

and

$$
M \int_{[0,1]-J} P(x) d x=M\left[Q\left(x_{0}\right)-Q(0)+Q(1)-Q\left(y_{0}\right)\right]=\frac{M}{M+1}
$$

Corollary 1 provides an elementary proof of the well-known
Corollary 2. Let $f(x)$ be a bounded summable function on the interval $[0,1]$, such that

$$
\int_{0}^{1} x^{k} f(x) d x=0, \quad \text { for } \quad k=0,1,2, \ldots
$$

Then $f(x)$ vanishes at every point of continuity.
Proof. Assume that $|f(x)|<M$ for $x \in[0,1]$. Let $x_{1}, 0 \leqslant x_{1} \leqslant 1$, be a point of continuity of $f(x)$. If $f\left(x_{1}\right) \neq 0$ then we may assume that $f(x)>\eta>0$ in some interval $J$ as in Corollary 1 , containing $x_{1}$.

By Corollary 1, there exists a polynomial $P(x)(\not \equiv 0)$ such that

$$
\int_{J} P(x) d x=\frac{M}{\eta} \int_{[0,1]-J} P(x) d x
$$

In addition, we have

$$
\int_{J} f(x) P(x) d x>\eta \int_{J} P(x) d x=M \int_{[0,1]-J} P(x) d x
$$

and

$$
\left|\int_{[0,1]-J} f(x) P(x) d x\right|<M \int_{[0,1]-J} P(x) d x
$$

We obtain a contradiction, since $\int_{0}^{1} f(x) P(x) d x=0$ implies that

$$
\left|\int_{[0,1]-J} f(x) P(x) d x\right|=\int_{J} f(x) P(x) d x
$$

This completes the proof. In particular, if $f(x)$ is Riemann integrable, then it vanishes almost everywhere in the interval $[0,1]$.
It is interesting to relate Theorem A to a result which follows from a theorem due to Yamabe. He proved [6], using the Weierstrass approximation theorem, the following:

Given a continuous function $g(x)$ on $[0,1], n$ linear functionals $\Phi_{i}$ ( $i=1,2, \ldots, n$ ) on the space $C[0,1]$ and a positive number $\epsilon$, there exists a polynomial $p(x)$ such that

$$
\max _{0 \leqslant x \leqslant 1}|g(x)-p(x)|<\epsilon
$$

and

$$
\Phi_{i}[g(x)]=\Phi_{i}[p(x)] .
$$

If this result is used, Theorem A (with (b) asserted only on [0,1]) can be proved by choosing a function $g(x)$ such that

$$
\begin{gathered}
g(x) \geqslant c>0 \quad \text { for } \quad 0 \leqslant x \leqslant 1, \\
\int_{0}^{x_{1}} g(t) d t=y_{1}, \quad \int_{x_{k-1}}^{x_{k}} g(t) d t=y_{k}-y_{k-1}, \quad k=2, \ldots, n
\end{gathered}
$$

and defining the $\Phi_{i}$ by $\Phi_{i}(h)=\int_{0}^{x_{i}} h(t) d t$. The theorem then follows by Yamabe's result, with $\epsilon=c / 2 .{ }^{1}$

Normally, in a uniform approximation process by polynomials, it is desirable to carry over as many properties of the approximated function $f(x)$ as possible.

For example, the Bernstein polynomials

$$
B_{n}(x)=\sum_{k=0}^{n}\binom{n}{k} x^{k}(1-x)^{n-k} f\left(\frac{k}{n}\right)
$$

[^0]are strictly increasing on the interval $[0,1]$, if $f(x)$ is also. A similar result holds [3] if $f(x)$ is starlike in [0,1] (that is, $f(\alpha x) \leqslant \alpha f(x)$ for $\alpha \in[0,1]$, $x \in[0,1])$. It would be, therefore, of interest to study properties which are inherited from a monotonic function to monotonic polynomials approximating it.

In the case of a three-point interpolation, one can actually construct a polynomial of the type of $Q(x)$ of Theorem A. Indeed, if $0<a<b$, $0<\rho<1$, one verifies easily that the polynomial

$$
R(x)=c\left[1-x^{n}-(1-x)^{n}\right]+b x^{n}
$$

where

$$
c=\frac{a-b \rho^{n}}{1-\rho^{n}-(1-\rho)^{n}},
$$

is strictly increasing and satisfies $P(0)=0, P(\rho)=a$, and $P(1)=b$, provided $n$ is a sufficiently large odd positive integer. It is enough to satisfy the conditions

$$
1-\left(1-\frac{a}{b}\right)^{1 / n}<\rho<\left(\frac{a}{b}\right)^{1 / n}
$$

since this implies that $0<c<b$. Thus, the minimal admissible $n$ depends only on $\rho$ and the ratio $a / b$. It would be interesting to estimate the minimal degree of a $Q(x)$ satisfying (a) and (b) of Theorem A.

## Acknowledgment

I wish to thank Dr. Oved Shisha for many valuable suggestions.

## References

1. N. I. Achiezer, "Lectures on Approximation Theory," Moscow, 1965.
2. G. G. Lorentz and K. L. Zeller, Degree of approximation by monotone polynomials, J. Approx. Theory 1 (1968), 501-504.
3. Lupas Liciana, A property of the S. N. Bernstein operator, Mathematika 9 (2) (1967), 299-301.
4. John A. Roulier, Monotone approximation of certain classes of functions, J. Approx. Theory 1 (1968), 319-324.
5. O. Shisha, Monotone approximation, Pacific J. Math. 15 (1965), 667-671.
6. Hidehiko Yamabe, On an extension of Helly's Theorem, Osaka Math. J. 2 (1950), 15-17.

[^0]:    ${ }^{1}$ This proof and the reference to Yamabe's paper were suggested by the referee, to whom I am greatly indebted.

